

Recall: $\frac{d\vec{u}}{dt} = -f\hat{k} \times \vec{u} - \vec{\nabla}_p \phi$ ① Coriolis ② PGF } when in balance, $\frac{d\vec{u}}{dt} = 0$

↳ ① ↳ ②

Geostrophy ⚡

What about when $\frac{d\vec{u}}{dt} \neq 0$? Quasi-geostrophy Yay!

QG w derivation

Start w/ QGS and T equations:

① QGS: $\frac{\partial S_g}{\partial t} = -\vec{V}_g \cdot \vec{\nabla}_p S_g - \beta v_g - \sigma F_g - K S_g$

↳ ① ↳ ② ↳ ③ ↳ ④

① "horizontal" advection of S ($S_g + f$)

② same for f

③ stretching of f

④ frictional effects (small: $\frac{\partial F_x}{\partial x} - \frac{\partial F_y}{\partial y} = -K S_g$)

② QGT: $\frac{\partial T}{\partial t} = -\vec{V}_g \cdot \vec{\nabla}_p T + w \frac{\partial p}{\partial p} + \frac{1}{c_p} \frac{dQ}{dt}$

↳ ① ↳ ② ↳ ③

① "horizontal" advection

② vertical motion

③ diabatic effects

$$\sigma = -\frac{RT}{p} \frac{\partial \ln \theta}{\partial p}$$

"static stability parameter"

Now, assume:

→ Adiabatic ($Q=0$)

→ Frictionless ($K=0$)

→ Constant f plane ($\beta=0$)

This simplifies ① & ② too...

$$\textcircled{1} \frac{\partial s_g}{\partial t} = -\vec{v}_g \cdot \vec{\nabla}_r s_g - s_g f_0 \Rightarrow \frac{1}{f_0} \vec{\nabla}^2 \frac{\partial \phi}{\partial t} = -\vec{v}_g \cdot \vec{\nabla}_r \left(\frac{1}{f_0} \vec{\nabla}^2 \phi + s_g \right) + f_0 \frac{\partial \omega}{\partial p}$$

$$\textcircled{2} \frac{\partial T}{\partial t} = -\vec{v}_g \cdot \vec{\nabla}_r T + \omega \sigma \frac{P}{R}$$

We can express s_g in terms of χ ...

$$s_g \equiv \frac{\partial u_s}{\partial x} - \frac{\partial v_s}{\partial y} = \frac{\partial}{\partial x} \left(\frac{1}{f_0} \frac{\partial \phi}{\partial x} \right) - \frac{\partial}{\partial y} \left(-\frac{1}{f_0} \frac{\partial \phi}{\partial y} \right) \left(\text{and } s_g = -\frac{\partial \omega}{\partial p} \right)$$

$$= \frac{1}{f_0} \left[\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right] = \frac{1}{f_0} \vec{\nabla}^2 \phi$$

So now we have:

$$\left\{ \begin{array}{l} \textcircled{1} \frac{1}{f_0} \vec{\nabla}^2 \chi = -\vec{v}_g \cdot \vec{\nabla}_r \left(\frac{1}{f_0} \vec{\nabla}^2 \phi + s_g \right) + f_0 \frac{\partial \omega}{\partial p} \\ \textcircled{2} -\frac{\partial}{\partial p} \left(\frac{\partial \phi}{\partial t} \right) = \vec{v}_g \cdot \vec{\nabla} \left(\frac{\partial \phi}{\partial p} \right) + \sigma \omega \quad (\text{sub } T = -\frac{\partial \phi}{\partial p}) \text{ "thickness"} \end{array} \right\}$$

Step 1: Take $f_0 \frac{\partial}{\partial p} (\textcircled{1})$

$$f_0 \frac{\partial}{\partial p} \left[\frac{1}{f_0} \vec{\nabla}^2 \chi \right] = f_0 \frac{\partial}{\partial p} \left[-\vec{v}_g \cdot \vec{\nabla}_r \left(\frac{1}{f_0} \vec{\nabla}^2 \phi + s_g \right) \right] + f_0 \frac{\partial}{\partial p} \left[f_0 \frac{\partial \omega}{\partial p} \right]$$

$$\textcircled{a} \frac{\partial}{\partial p} \left(\vec{\nabla}^2 \frac{\partial \phi}{\partial t} \right) = f_0 \frac{\partial}{\partial p} \left(-\vec{v}_g \cdot \vec{\nabla}_r (s_g + f) \right) + f_0^2 \frac{\partial^2 \omega}{\partial p^2}$$

Step 2: Take $\vec{\nabla}^2 (\textcircled{2})$

$$\textcircled{b} \vec{\nabla}^2 \left(-\frac{\partial}{\partial p} \left(\frac{\partial \phi}{\partial t} \right) \right) = \vec{\nabla}^2 \left(\vec{v}_g \cdot \vec{\nabla} \frac{\partial \phi}{\partial p} \right) + \sigma \vec{\nabla}^2 \omega$$

Step 3: $\textcircled{a} + \textcircled{b}$ (LHS = 0)

$$0 = f_0 \frac{\partial}{\partial p} (-\vec{v}_g \cdot \vec{\nabla}(\zeta_g + \zeta)) + f_0^2 \frac{\partial^2 \omega}{\partial p^2} + \vec{\nabla}^2 (\vec{v}_g \cdot \vec{\nabla} \frac{\partial \phi}{\partial p}) + \sigma \vec{\nabla}^2 \omega$$

Rearrange...

$$-\sigma \vec{\nabla}^2 \omega - f_0^2 \frac{\partial^2 \omega}{\partial p^2} = f_0 \frac{\partial}{\partial p} (-\vec{v}_g \cdot \vec{\nabla}(\zeta_g + \zeta)) + \vec{\nabla}^2 (\vec{v}_g \cdot \vec{\nabla} (\frac{\partial \phi}{\partial p}))$$

Multiply by -1 and combine LHS:

$$\underbrace{(\sigma \vec{\nabla}^2 + f_0^2 \frac{\partial^2}{\partial p^2})}_{\textcircled{1}} \omega = - \underbrace{f_0 \frac{\partial}{\partial p} (-\vec{v}_g \cdot \vec{\nabla}(\zeta_g + \zeta))}_{\textcircled{2}} - \underbrace{\vec{\nabla}^2 (\vec{v}_g \cdot \vec{\nabla} (-\frac{\partial \phi}{\partial p}))}_{\textcircled{3}}$$

① $\sim -\omega$ ($\omega > 0$)

② Differential vorticity advection

③ Temperature advection

Key takeaways:

① For lower stability ($\sigma \downarrow$) and equal forcing (RHS), ω increases

② Increasing CVA w/ height $\Rightarrow$ rising motion

$$\frac{\partial}{\partial z} (-\vec{v}_g \cdot \vec{\nabla} \zeta) > 0 \Rightarrow -\frac{\partial}{\partial p} (-\vec{v}_g \cdot \vec{\nabla} \zeta) > 0 \Rightarrow \boxed{-\omega} \Rightarrow \boxed{\omega > 0}$$

③ WAA $\Rightarrow$ rising motion

$$-\vec{v}_g \cdot \vec{\nabla} (-\frac{\partial \phi}{\partial p}) > 0 \Rightarrow \vec{\nabla}^2 (\dots) < 0 \Rightarrow -\vec{\nabla}^2 (\dots) > 0 \Rightarrow \boxed{\omega < 0} \Rightarrow \boxed{\omega > 0}$$

END

See "Lecture 2-ish" for examples

QG χ derivation:

(4)

Back to our starting equations...

$$\textcircled{1} \frac{1}{f_0} \vec{\nabla}_p^2 \chi = -\vec{v}_g \cdot \vec{\nabla}_p \left(\frac{1}{f_0} \vec{\nabla}^2 \phi + f \right) + f_0 \frac{\partial \omega}{\partial p}$$

$$\textcircled{2} -\frac{\partial}{\partial p} \chi = -\vec{v}_g \cdot \vec{\nabla}_p \left(\frac{\partial \phi}{\partial p} \right) + \sigma \omega$$

Step 1: Take f_0 (1)

$$\textcircled{a} \vec{\nabla}_p^2 \chi = f_0 \left(-\vec{v}_g \cdot \vec{\nabla}_p \left(\frac{1}{f_0} \vec{\nabla}^2 \phi + f \right) \right) + f_0^2 \frac{\partial \omega}{\partial p}$$

Step 2: Take $-\frac{f_0^2}{\sigma} \frac{\partial}{\partial p}$ (2)

$$-\frac{f_0^2}{\sigma} \frac{\partial}{\partial p} \left(-\frac{\partial \chi}{\partial p} \right) = -\frac{f_0^2}{\sigma} \frac{\partial}{\partial p} \left(\vec{v}_g \cdot \vec{\nabla} \left(\frac{\partial \phi}{\partial p} \right) \right) - \frac{f_0^2}{\sigma} \frac{\partial}{\partial p} (\sigma \omega)$$

$$\textcircled{b} \frac{f_0^2}{\sigma} \frac{\partial^2}{\partial p^2} \chi = \frac{f_0^2}{\sigma} \frac{\partial}{\partial p} \left(-\vec{v}_g \cdot \vec{\nabla} \left(\frac{\partial \phi}{\partial p} \right) \right) - f_0^2 \frac{\partial \omega}{\partial p} \quad \leftarrow \text{assume } \frac{\partial \sigma}{\partial p} = 0 (!!)$$

Step 3: (a) + (b) (last term cancels)

$$\boxed{\left(\vec{\nabla}_p^2 + \frac{\partial^2}{\partial p^2} \right) \chi = f_0 \left(-\vec{v}_g \cdot \vec{\nabla}_p (f_g + f) \right) - \frac{f_0^2}{\sigma} \frac{\partial}{\partial p} \left(-\vec{v}_g \cdot \vec{\nabla} \left(-\frac{\partial \phi}{\partial p} \right) \right)}$$

①②③

① $\sim -\chi$ (height falls)

② vorticity advection

③ Differential temperature advection

Key takeaways:

① Not dependent on static stability

② CVA $\Rightarrow$ height rolls

$$-\vec{U}_g \cdot \vec{OS} > 0 \Rightarrow \chi < 0$$

③ DCAA $\Rightarrow$ height rolls

$$\frac{\partial}{\partial \tau} \left[-\vec{U}_g \cdot \vec{\nabla} \left(-\frac{\partial \Phi}{\partial p} \right) \right] < 0 \Rightarrow -\frac{\partial}{\partial p} (\dots) > 0 \Rightarrow \chi < 0$$

END

See "lecture 2-Bh" for examples

